

# The classification of root systems

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The elements of  $R$  are called *roots*.

The *rank* of the root system is the dimension of  $\mathbb{E}$ .

# Restrictions

## Projection

$$\text{proj}_{\alpha} \beta = \alpha \frac{\langle \beta, \alpha \rangle}{\langle \alpha, \alpha \rangle} = \frac{1}{2} n_{\beta\alpha} \alpha$$



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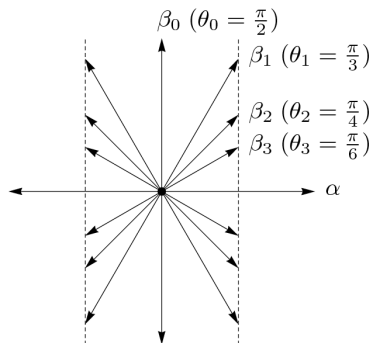
## Angles

$$n_{\beta\alpha} = 2 \frac{\langle \beta, \alpha \rangle}{\langle \alpha, \alpha \rangle} = 2 \frac{\|\beta\| \|\alpha\| \cos \theta}{\|\alpha\|^2} = 2 \frac{\|\beta\|}{\|\alpha\|} \cos \theta \in \mathbb{Z}$$

$$n_{\beta\alpha} \cdot n_{\alpha\beta} = 4 \cos^2 \theta \in \mathbb{Z}$$

$$4 \cos^2 \theta \in \{0, 1, 2, 3, 4\}$$

# Geometry

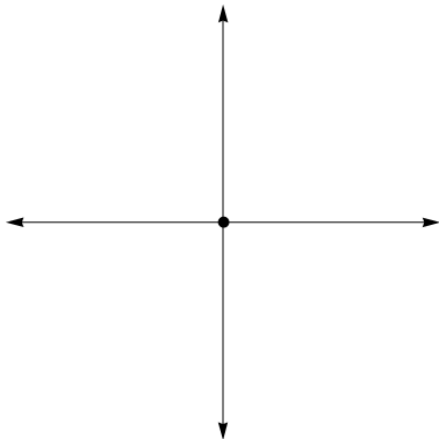


## Angles

$$4 \cos^2 \theta \in \{0, 1, 2, 3\}, \text{ or } \cos \theta \in \pm \left\{ 0, \frac{1}{2}, \frac{\sqrt{2}}{2}, \frac{\sqrt{3}}{2} \right\}$$

## Examples in rank 2

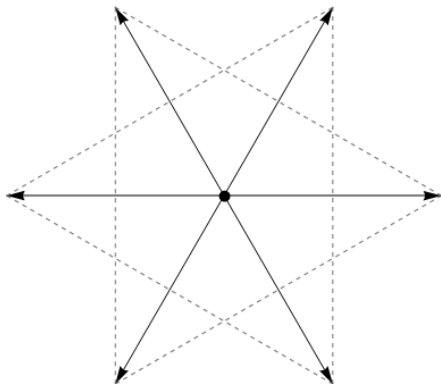
Root system  $A_1 \times A_1$



(decomposable)

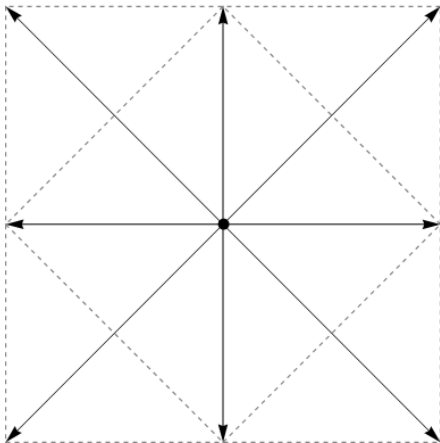
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Root system  $A_2$



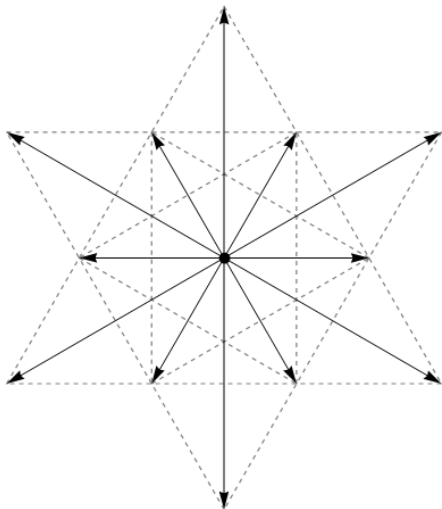
## Examples in rank 2

Root system  $B_2$



# Examples in rank 2

Root system  $G_2$



## Positive roots and simple roots

Consider a vector  $d$ , such that  $\forall \alpha \in R : \langle \alpha, d \rangle \neq 0$ . Define  $R^+(d) = \{\alpha \in R \mid \langle \alpha, d \rangle > 0\}$ . Then  $R = R^+(d) \cup R^-(d)$ , where  $R^-(d) = -R^+(d)$ .

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### Definition

The set of all simple roots of a root system  $R$  is called *basis* of  $R$ .

# Properties of simple roots

## Definition

The hyperplanes orthogonal to  $\alpha \in R$  cut the space  $\mathbb{E}$  into open, connected regions called *Weyl chambers*.

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## Lemma

*The root system  $R$  can be uniquely reconstructed from its basis.*

# Coxeter and Dynkin diagrams

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*If  $\alpha$  and  $\beta$  are distinct simple roots, then  $\langle \alpha, \beta \rangle \leq 0$ .*



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## Conclusion

Since  $4 \cos^2 \theta \in \{0, 1, 2, 3\}$ , it means that  $\theta \in \left\{ \frac{\pi}{2}, \frac{2\pi}{3}, \frac{3\pi}{4}, \frac{5\pi}{6} \right\}$ .

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The *Coxeter graph* of a root system  $R$  is a graph that has one vertex for each simple root of  $R$  and every pair  $\alpha, \beta$  of distinct vertices is connected by  $n_{\alpha\beta} \cdot n_{\beta\alpha} = 4 \cos^2 \theta \in \{0, 1, 2, 3\}$  edges.

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## Definition

The *Dynkin diagram* of a root system is its Coxeter graph with arrow attached to each double and triple edge pointing from longer root to shorter root.

# Admissible diagrams

## Definition

A set of  $n$  unit vectors  $\{v_1, v_2, \dots, v_n\} \subset \mathbb{E}$  is called an *admissible configuration* if:

1.  $v_i$ 's are linearly independent and span  $\mathbb{E}$ ,
2. if  $i \neq j$ , then  $\langle v_i, v_j \rangle \leq 0$ ,
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## Note

The set of normalized simple roots of any root system is an admissible configuration (they are linearly independent, span the whole space, and have specific angles between them).

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Coxeter graph of an admissible configuration is *admissible diagram*.

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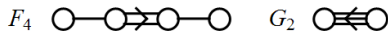
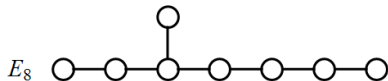
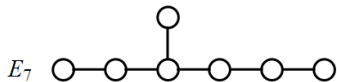
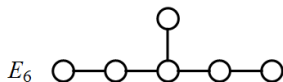
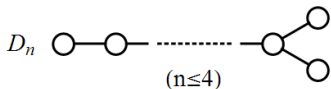
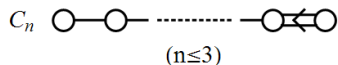
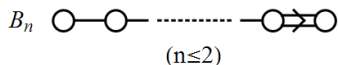
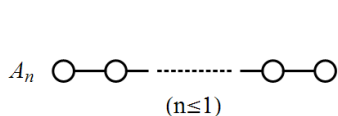
## Conclusion

It means, the set of simple roots of an irreducible root system can not be decomposed into mutually orthogonal subsets. Hence the corresponding Coxeter graph will be *connected*. Thus, to classify all irreducible root systems, it is enough to consider only connected admissible diagrams.

# Classification theorem

## Theorem

The Dynkin diagram of an irreducible root system is one of:



# Step 1

**Claim:** *Any subdiagram of an admissible diagram is also admissible.*

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If the set  $\{v_1, v_2, \dots, v_n\}$  is an admissible configuration, then clearly any subset of it is also an admissible configuration (in the space it spans). The same holds for admissible diagrams.

## Step 2

**Claim:** *A connected admissible diagram is a tree.*

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Define  $v = \sum_{i=1}^n v_i$  ( $v \neq 0$ ). Then

$$0 < \langle v, v \rangle = \sum_{i=1}^n \langle v_i, v_i \rangle + \sum_{i < j} 2 \langle v_i, v_j \rangle = n + \sum_{i < j} 2 \langle v_i, v_j \rangle.$$

If  $v_i$  and  $v_j$  are connected, then

$$2 \langle v_i, v_j \rangle \in \{-1, -\sqrt{2}, -\sqrt{3}\}$$

In particular,  $2 \langle v_i, v_j \rangle \leq -1$ . It means, the number of terms in the sum and hence the number of edges can not exceed  $n - 1$ .

## Step 3

**Claim:** *No more than three edges (counting multiplicities) can originate from the same vertex.*

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Let  $v_1, v_2, \dots, v_k$  be connected to  $c$ , then  $\langle v_i, v_j \rangle = \delta_{ij}$ . Let  $v_0 \neq 0$  be the normalized projection of  $c$  to the orthogonal complement of  $v_i$ 's. Then  $\{v_0, v_1, v_2, \dots, v_k\}$  is an orthonormal basis and:

$$c = \sum_{i=0}^k \langle c, v_i \rangle v_i.$$

Since  $\langle c, c \rangle = \sum_{i=0}^k \langle c, v_i \rangle^2 = 1$  and  $\langle c, v_0 \rangle \neq 0$ , then

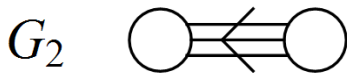
$$\sum_{i=1}^k 4 \langle c, v_i \rangle^2 < 4,$$

where  $4 \langle c, v_i \rangle^2$  is the number of edges between  $c$  and  $v_i$ .



## Step 4

**Claim:** *The only connected admissible diagram containing a triple edge is*



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This follows from the previous step. From now on we will consider only diagrams with single and double edges.

## Step 5

**Claim:** Any simple chain  $v_1, v_2, \dots, v_k$  can be replaced by a single vector  $v = \sum_{i=1}^k v_i$ .

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Vector  $v$  is a unit vector, since  $2 \langle v_i, v_j \rangle = -\delta_{i+1,j}$  and therefore

$$\langle v, v \rangle = k + \sum_{i < j} 2 \langle v_i, v_j \rangle = k + \sum_{i=1}^{k-1} 2 \langle v_i, v_{i+1} \rangle = k - (k-1) = 1.$$

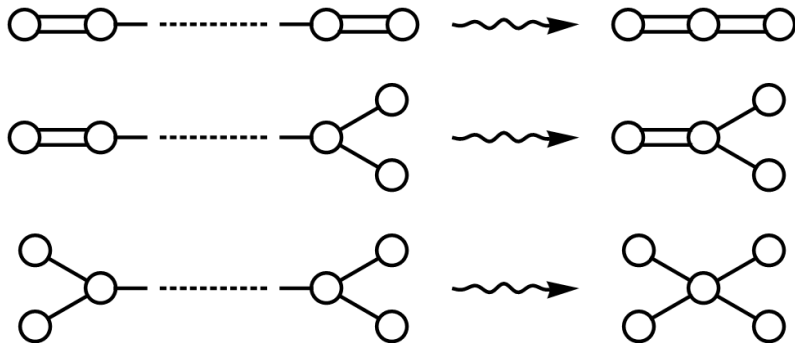
If  $u$  is not in the chain, then it can be connected to at most one vertex in the chain (let it be  $v_j$ ). Then

$$\langle u, v \rangle = \sum_{i=1}^k \langle u, v_i \rangle = \langle u, v_j \rangle$$

and  $u$  remains connected to  $v$  in the same way. Therefore the obtained diagram is also admissible and connected.

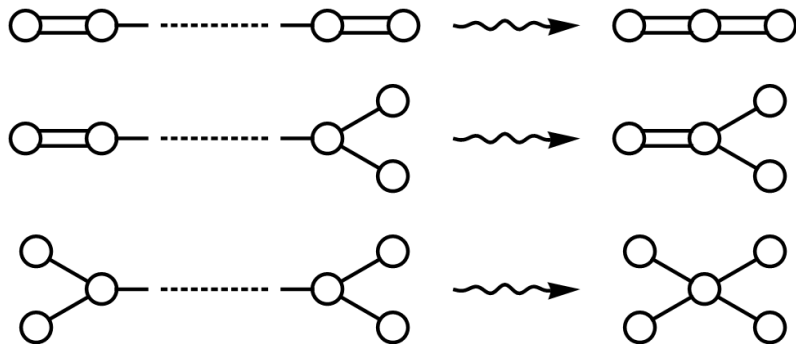
## Step 6

**Claim:** A connected admissible diagram has none of the following subdiagrams:



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## Conclusion

It means that a connected admissible diagram can contain at most one double edge and at most one branching, but not both of them simultaneously.

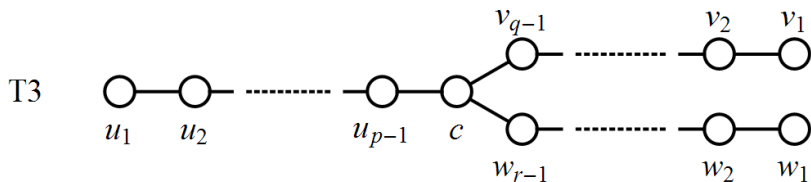
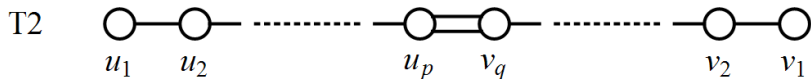
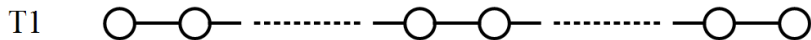
## Step 7

**Claim:** *There are only three types of connected admissible diagrams:*

**T1:** *a simple chain,*

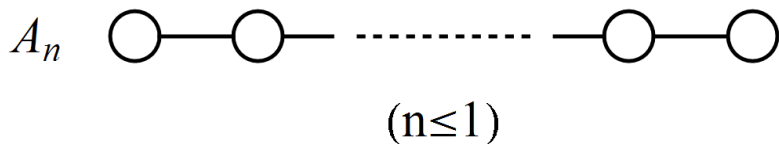
**T2:** *a diagram with a double edge,*

**T3:** *a diagram with branching.*



## Step 8

**Claim:** *The admissible diagram of type T1 corresponds to the Dynkin diagram  $A_n$ , where  $n \geq 1$ .*





## Step 9

**Claim:** *The admissible diagrams of type T2 are  $F_4$ ,  $B_n$ , and  $C_n$ .*

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**Claim:** The admissible diagrams of type T2 are  $F_4$ ,  $B_n$ , and  $C_n$ .

Define  $u = \sum_{i=1}^p i \cdot u_i$ . Since  $2 \langle u_i, u_{i+1} \rangle = -1$  for  $1 \leq i \leq p-1$ ,

$$\begin{aligned} \langle u, u \rangle &= \sum_{i=1}^p i^2 \langle u_i, u_i \rangle + \sum_{i < j} ij \cdot 2 \langle u_i, u_j \rangle = \sum_{i=1}^p i^2 - \sum_{i=1}^{p-1} i(i+1) \\ &= p^2 - \sum_{i=1}^{p-1} i = p^2 - \frac{p(p-1)}{2} = \frac{p(p+1)}{2}. \end{aligned}$$

Similarly,  $v = \sum_{j=1}^q j \cdot v_j$  and  $\langle v, v \rangle = q(q+1)/2$ . From

$\langle u, v \rangle = pq \langle u_p, v_q \rangle$  and  $4 \langle u_p, v_q \rangle^2 = 2$  we get  $\langle u, v \rangle^2 = p^2 q^2 / 2$ .

From Cauchy-Schwarz inequality  $\langle u, v \rangle^2 < \langle u, u \rangle \langle v, v \rangle$  we get

$$\frac{p^2 q^2}{2} < \frac{p(p+1)}{2} \cdot \frac{q(q+1)}{2}.$$

## Step 10 (continued)

Since  $p, q \in \mathbb{Z}_+$ , we get  $2pq < (p + 1)(q + 1)$  or simply  $(p - 1)(q - 1) < 2$ .

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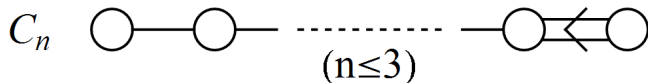
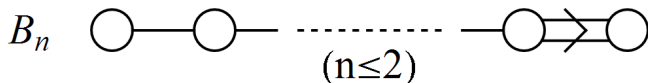
## Step 10 (continued)

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$$p = q = 2$$



$p = 1$  and  $q$  is arbitrary (or vice versa)



## Step 10

**Claim:** *The admissible diagrams of type T3 are  $D_n$ ,  $E_6$ ,  $E_7$ ,  $E_8$ .*

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**Claim:** *The admissible diagrams of type T3 are  $D_n, E_6, E_7, E_8$ .*

Define  $u = \sum_{i=1}^{p-1} i \cdot u_i$ ,  $v = \sum_{j=1}^{q-1} j \cdot v_j$ , and  $w = \sum_{k=1}^{r-1} k \cdot w_k$ . Let  $u'$ ,  $v'$ , and  $w'$  be the corresponding unit vectors. Then

$$1 = \langle c, c \rangle > \langle c, u' \rangle^2 + \langle c, v' \rangle^2 + \langle c, w' \rangle^2.$$

Since  $\langle c, u_i \rangle^2 = 0$  unless  $i = p - 1$  and  $4 \langle c, u_{p-1} \rangle^2 = 1$ , we have

$$\langle c, u \rangle^2 = \sum_{i=1}^{p-1} i^2 \langle c, u_i \rangle^2 = (p-1)^2 \langle c, u_{p-1} \rangle^2 = \frac{(p-1)^2}{4}.$$

We already know that  $\langle u, u \rangle = p(p-1)/2$ , therefore

$$\langle c, u' \rangle^2 = \frac{\langle c, u \rangle^2}{\langle u, u \rangle} = \frac{(p-1)^2}{4} \cdot \frac{2}{p(p-1)} = \frac{p-1}{2p} = \frac{1}{2} \left( 1 - \frac{1}{p} \right).$$

## Step 10 (Continued)

If we do the same for  $v$  and  $w$ , we get

$2 > (1 - 1/p) + (1 - 1/q) + (1 - 1/r)$  or simply

$$\frac{1}{p} + \frac{1}{q} + \frac{1}{r} > 1, \quad p, q, r \geq 2.$$



## Step 10 (Continued)

If we do the same for  $v$  and  $w$ , we get  
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We can assume that  $p \geq q \geq r \geq 2$ . There is no solution with  $r \geq 3$ , since then the sum can not exceed 1. Therefore we have to take  $r = 2$ . If we take  $q = 2$  as well, then any  $p$  suits, but for  $q = 3$  we have  $1/q + 1/r = 5/6$  and we can take only  $p < 6$ . There are no solutions with  $q \geq 4$ , because then the sum is at most 1.

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$p$	$q$	$r$	Dynkin diagram
any	2	2	$D_n$
3	3	2	$E_6$
4	3	2	$E_7$
5	3	2	$E_8$

End of proof

**Q.E.D.**

End of proof

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### Theorem

*For each Dynkin diagram we have found there indeed is an irreducible root system having the given diagram.*